

Reconciling mathematics with programming for developing sustainable HPC codes in continuum mechanics

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Advanced Computing User Day 2024, Utrecht, the Netherlands



Continuum Mechanics

Fluids:

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u}) = -\nabla P + \nabla \cdot \mathbf{S} + \rho g$$

Solids:

$$\rho \frac{\partial^2 \mathbf{x}}{\partial t^2} = \nabla \cdot \mathbf{S} + \mathbf{F}$$



FLUENT

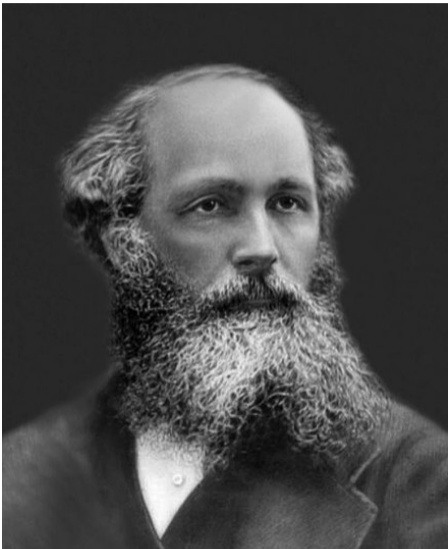
OpenFOAM



ReFresco

SIMULIA
ABAQUS

(Discrete) Vector Calculus



"it is evident that all analogies of this kind depend on principles of a more fundamental nature; and that [...] we should lose no time in availing ourselves of the mathematical labours of those who had already solved problems essentially the same"

J.C. Maxwell 1869

Challenge

*Can we systematize the **computational and numerical** aspects of computational mechanics?*

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- How to consider the parallel aspects?
- How to construct the discretizations?

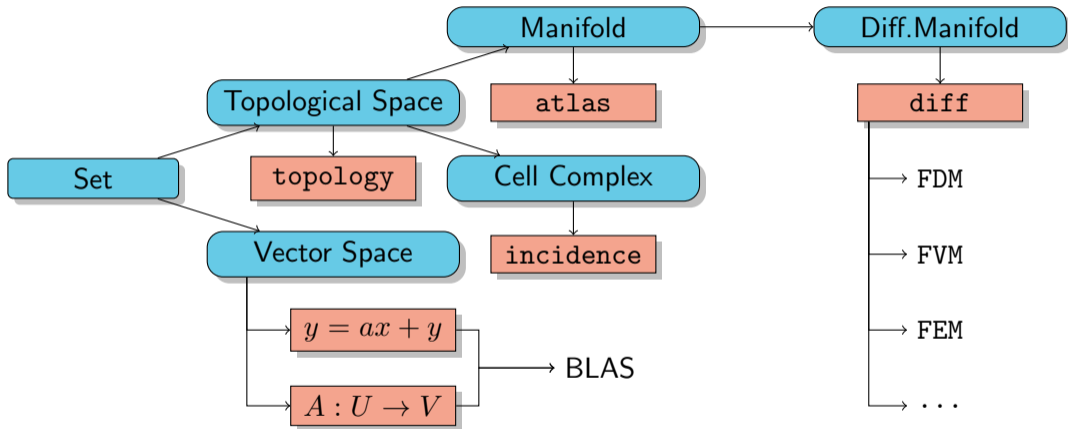
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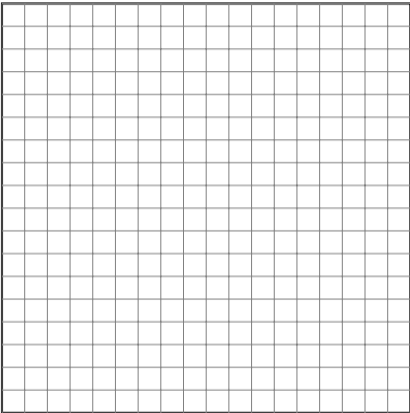
- How to consider the parallel aspects?
- How to construct the discretizations?

Set theory + OOP

Abstract Algebra

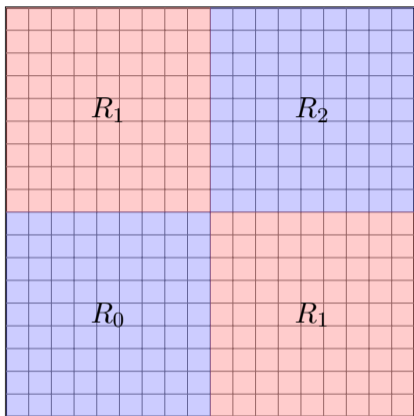


Partitions



□ memory

Partitions



□ memory

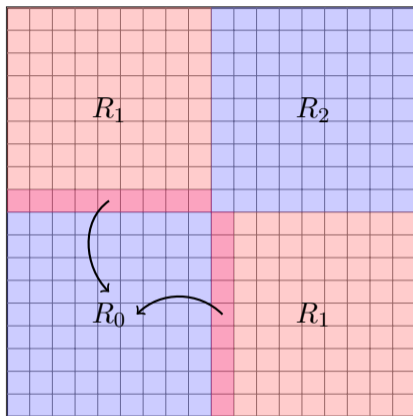
■ partition

Definition

A partition P of a set X is a *collection of subsets* such that:

- $\emptyset \notin P$
- $\bigcup_i P_i = X$
- $P_i \cap P_j | i \neq j = \emptyset$

Partitions



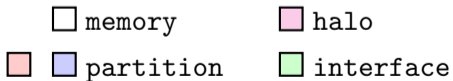
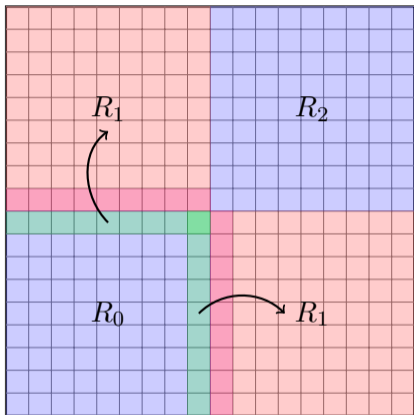
□ memory
□ halo
□ partition

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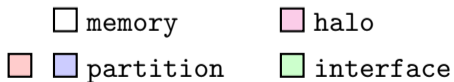
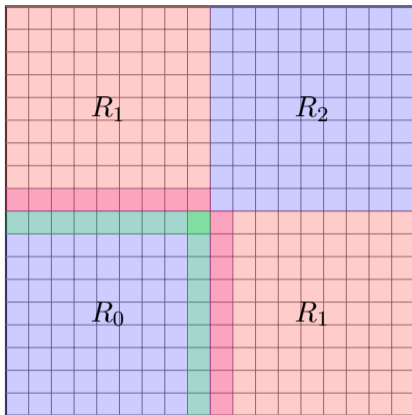


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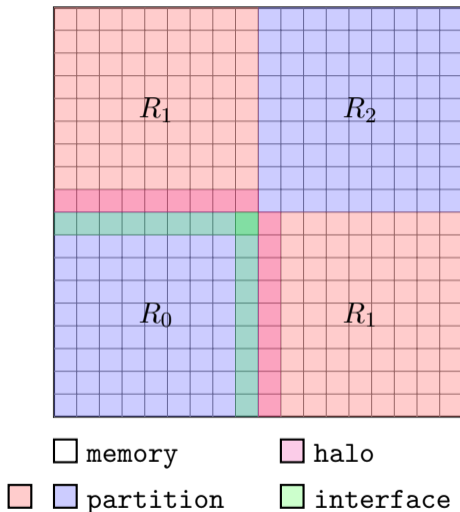


Definition

A cover C of a set X is a *collection of subsets* such that:

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- $\bigcup_i C_i \supset X$

Partitions



Definition

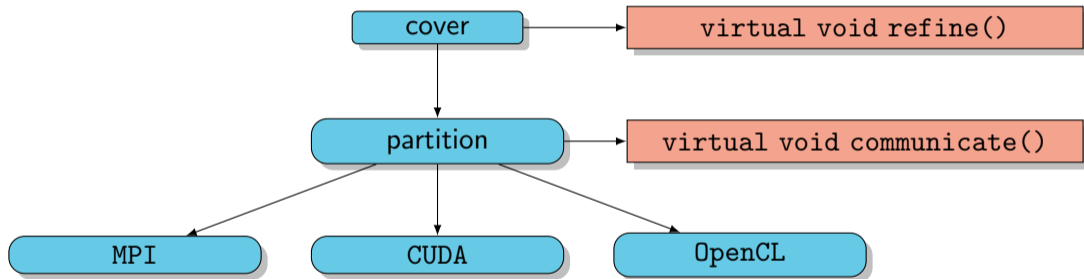
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Summary:

- set X memory
- partition P MPI_comm
- cover C halo/interface

Abstraction



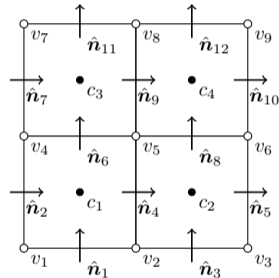
Mesh

What is a mesh?

Portability & Resilience

Why is it a challenge?

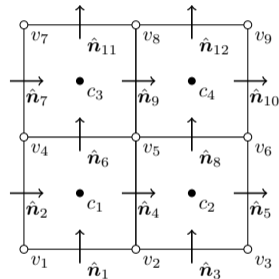
```
for(int i = 0; i < M; i++)  
{  
    ...  
    for(int j = 0; j < N; j++)  
    {  
        ...  
        y[i] = A[i][j] * x[i];  
        ...  
    }  
    ...  
}
```



Portability & Resilience

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Local memory accesses!

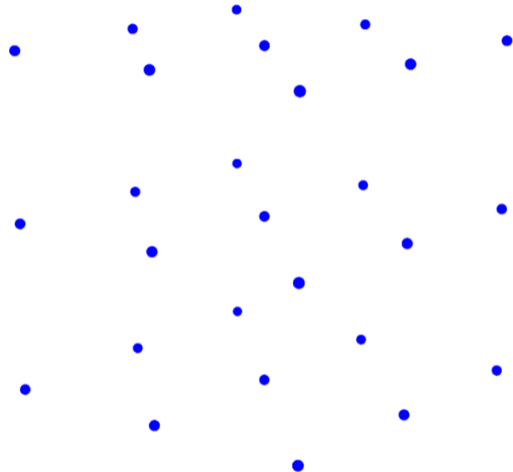
Connectivity - Cell complex

Connectivity - Cell complex

 P

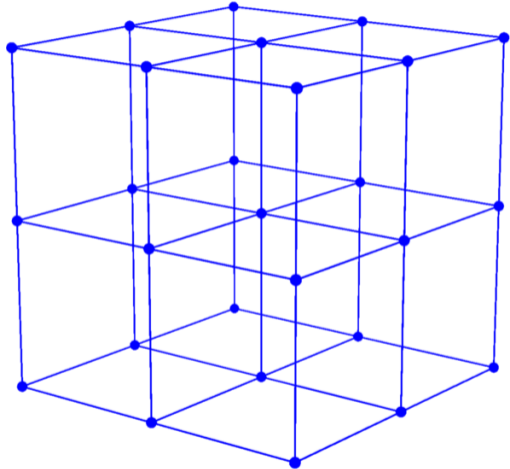
Connectivity - Cell complex

$$P \xrightarrow{E_0} L$$



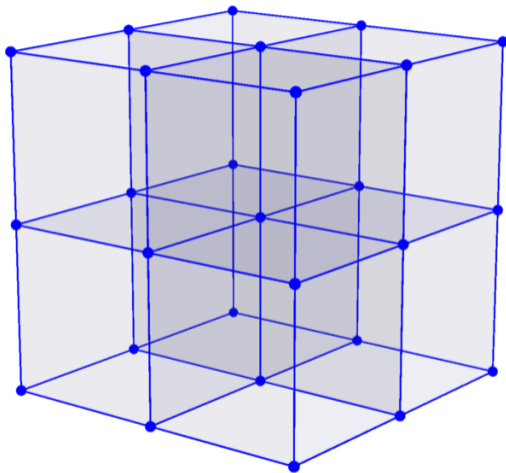
Connectivity - Cell complex

$$P \xrightarrow{E_0} L \xrightarrow{E_1} S$$



Connectivity - Cell complex

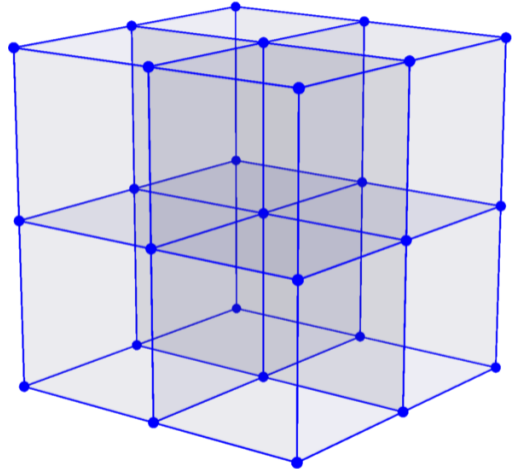
$$P \xrightarrow{E_0} L \xrightarrow{E_1} S \xrightarrow{E_2} V$$



Connectivity - Cell complex

co-chain

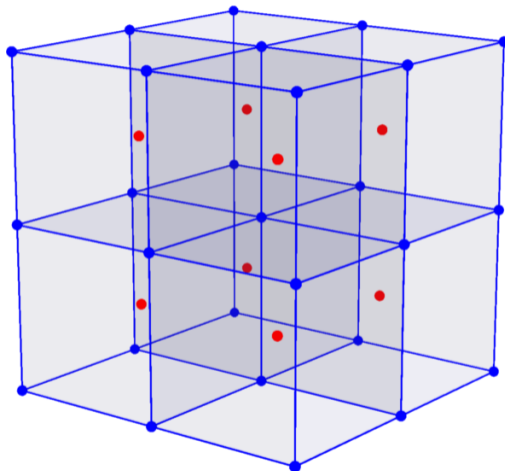
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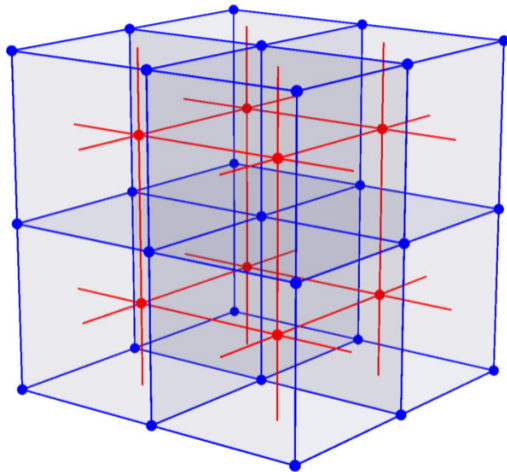
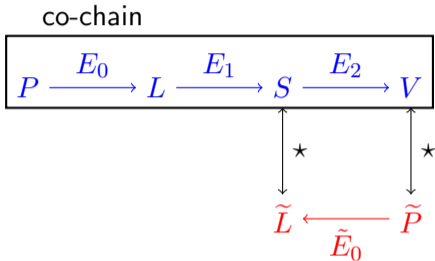
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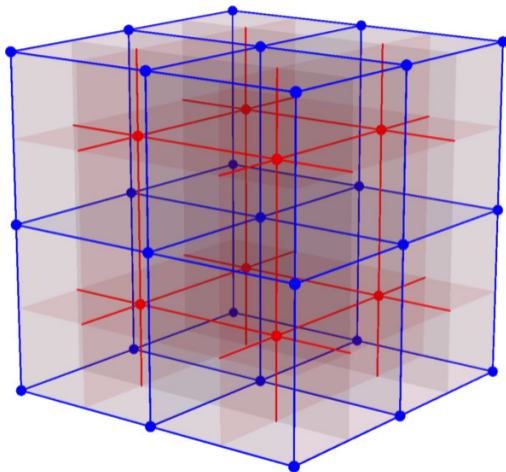
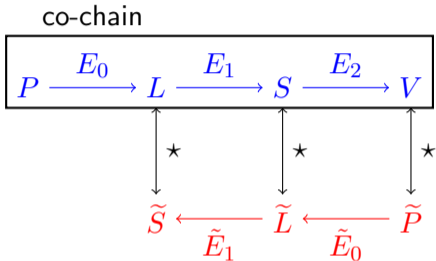
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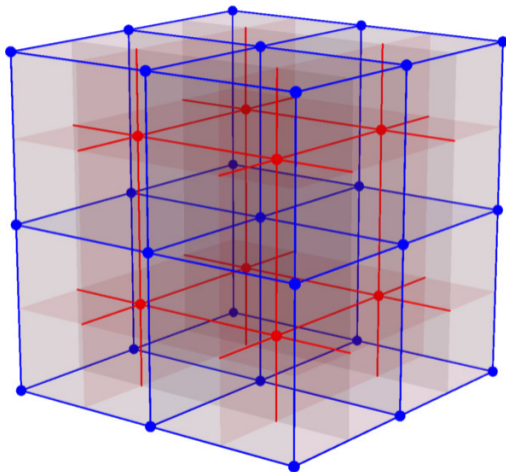
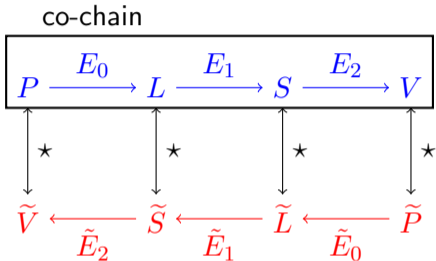
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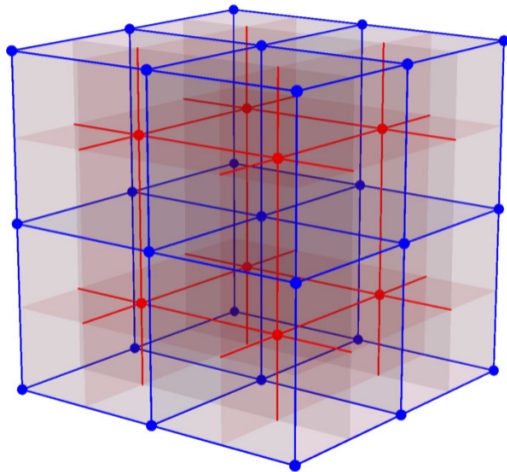
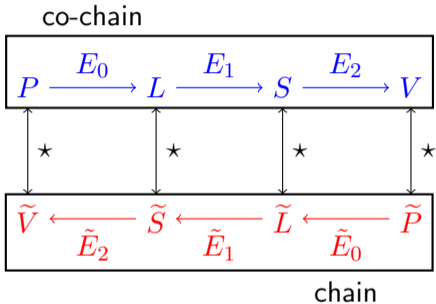
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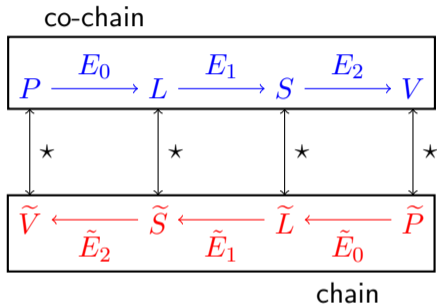
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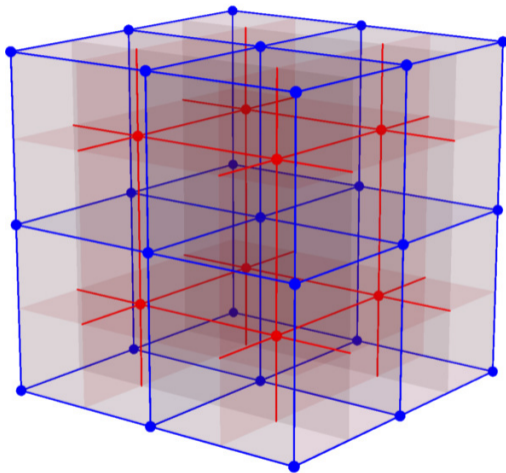


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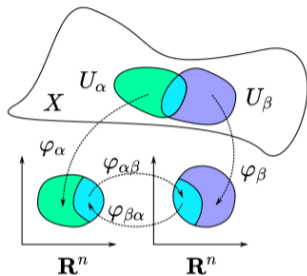


Summary:

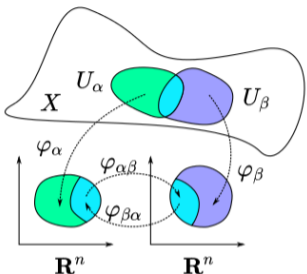
- C_i Cells!
- $E_i : C_i \rightarrow C_{i\pm 1}$ Connectivity!



Coordinates - Manifold



Coordinates - Manifold

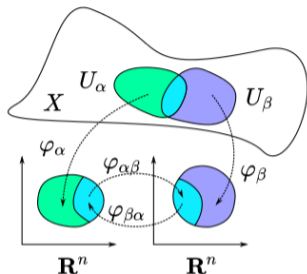


Definition

A manifold M is a topological space X equipped with a *collection of maps* φ that map to the Euclidean space \mathbb{R}^n .

$$\varphi_\alpha : U_\alpha \subseteq M \rightarrow \mathbb{R}^n$$

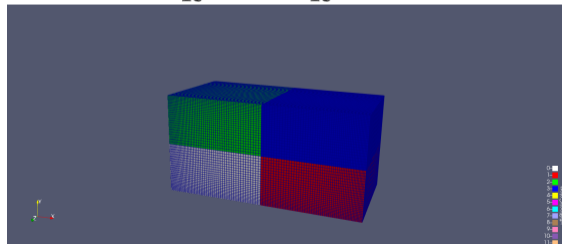
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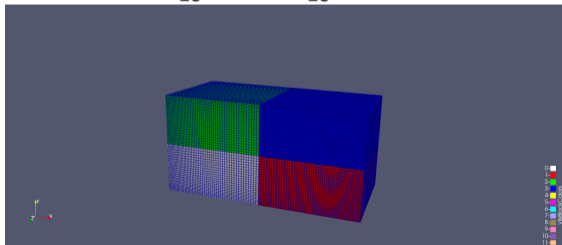
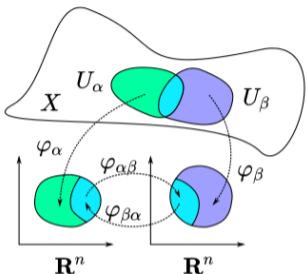
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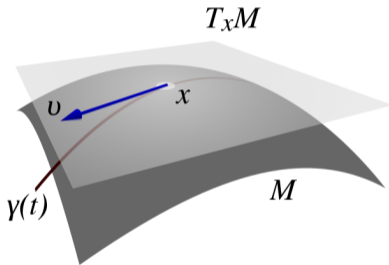
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Summary:

- atlas φ xdmf/vtk/etc
- manifold M mesh!

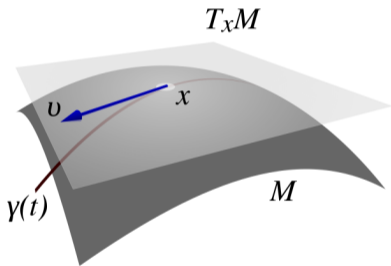
Differentials - Differential Manifold



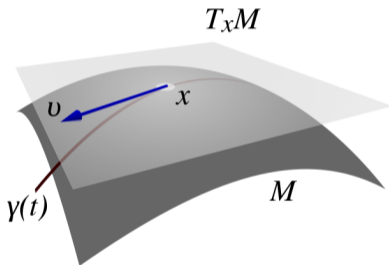
Differentials - Differential Manifold

Definition

A differential manifold M that is “smooth enough” to perform differentiation. This defines locally a tangent space $T_x M$.



Differentials - Differential Manifold



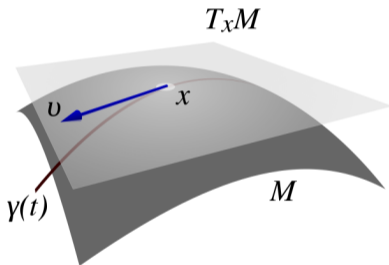
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$$f \quad fdl \quad fdS \quad fdv$$

$$\begin{array}{ccccccc}
 \Lambda_0 & \xrightarrow{d} & \Lambda_1 & \xrightarrow{d} & \Lambda_2 & \xrightarrow{d} & \Lambda_3 \\
 \downarrow f & & \downarrow f & & \downarrow f & & \downarrow f \\
 P & \xrightarrow{E_0} & L & \xrightarrow{E_1} & S & \xrightarrow{E_2} & V
 \end{array}$$

Differentials - Differential Manifold



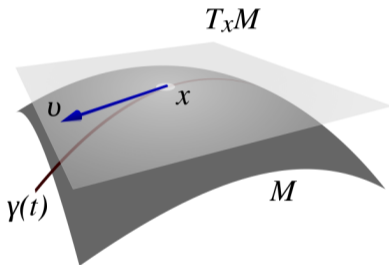
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Summary:

- Tangent Space $T_x M$ FDM/FVM/FEM/SEM

Summary

