CIEM5110-2: FEM, lecture 2.1

Derivation of the finite element method for Timoshenko beam elements

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Objectives

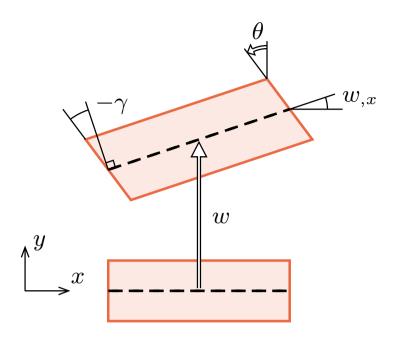
This lecture focuses on the formulation of the finite elmenent method for Timoshenko beams

- Another example of how to go from PDEs to the FE formulation
- Specifically for a case with multiple fields and multiple equations
- Illustration of shear locking
- Stepping stone towards frame analysis for upcoming workshops



The basic ingredients

Equilibrium relations	$M_{,x} - V = 0$
	$V_{,x} + q = 0$
Constitutive relations	$M = -EI\kappa$
	$V = GA_{\rm s}\gamma$
Kinematic relations	$\kappa = \theta_{,x}$
	$\gamma = w_{,x} - \theta$
Strong form equations	$-EI\theta_{,xx} - GA_{s}(w_{,x} - \theta) = 0$
	$GA_{\rm s}\left(w_{,xx}-\theta_{,x}\right)+q=0$



Some remarks:

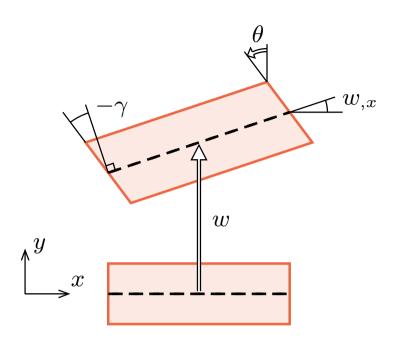
- Notations follow from Track Base except:
 - θ instead of φ for rotations
 - y (and w) are pointing upward
- The strong form has two coupled ODEs
- There are two unknown fields: w and θ



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The alternative would be an Euler beam:

- Single ODE but of 4th order
- Not treated in this unit
- FE derivation is given in the book



Discretized form

The coupled structure remains visisble in the system of equations

$$egin{bmatrix} \mathbf{K}_{ heta heta} & \mathbf{K}_{ heta w} \ \mathbf{K}_{w heta} & \mathbf{K}_{w w} \end{bmatrix} egin{bmatrix} \mathbf{a}_{ heta} \ \mathbf{a}_{w} \end{bmatrix} = egin{bmatrix} \mathbf{f}_{ heta} \ \mathbf{f}_{w} \end{bmatrix}$$

with

$$\mathbf{K}_{\theta\theta} = \int_{\Omega} \mathbf{B}_{\theta}^{T} E I \mathbf{B}_{\theta} + \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{N}_{\theta} \, \mathrm{d}\Omega$$

$$\mathbf{K}_{\theta w} = -\int_{\Omega} \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{B}_{w} \, \mathrm{d}\Omega$$

$$\mathbf{K}_{w\theta} = -\int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{N}_{\theta} \, \mathrm{d}\Omega$$

$$\mathbf{K}_{ww} = \int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{B}_{w} \, \mathrm{d}\Omega$$

$$\mathbf{f}_{\theta} = \int_{\Gamma_{M}} \mathbf{N}_{\theta}^{T} T \, \mathrm{d}\Gamma$$

$$\mathbf{f}_{w} = \int_{\Gamma_{M}} \mathbf{N}_{w}^{T} F \, \mathrm{d}\Gamma + \int_{\Omega} \mathbf{N}_{w}^{T} q \, \mathrm{d}\Omega$$



Extensible beam element

Combining the Timoshenko element with a bar element:

$$egin{bmatrix} \mathbf{K}_{uu}^{\mathrm{e}} & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{K}_{ww}^{\mathrm{e}} & \mathbf{K}_{w heta}^{\mathrm{e}} \ \mathbf{0} & \mathbf{K}_{ heta w}^{\mathrm{e}} & \mathbf{K}_{ heta heta}^{\mathrm{e}} \end{bmatrix} egin{bmatrix} \mathbf{a}_u \ \mathbf{a}_{ heta} \end{bmatrix} = egin{bmatrix} \mathbf{f}_u \ \mathbf{f}_w \ \mathbf{f}_{ heta} \end{bmatrix}$$

with

$$\mathbf{K}_{uu} = \int_{\Omega} \mathbf{B}_{u}^{T} E A \mathbf{B}_{u} \, d\Omega$$

$$\mathbf{f}_{u} = \int_{\Gamma_{N}} \mathbf{N}_{u}^{T} F_{x} \, d\Gamma + \int_{\Omega} \mathbf{N}_{u}^{T} q_{x} \, d\Omega$$

$$\mathbf{f}_{w} = \int_{\Gamma_{V}} \mathbf{N}_{w}^{T} F_{y} \, d\Gamma + \int_{\Omega} \mathbf{N}_{w}^{T} q_{y} \, d\Omega$$

$$\mathbf{f}_{\theta} = \int_{\Gamma_{M}} \mathbf{N}_{\theta}^{T} T \, d\Gamma$$

Now there are three coupled PDEs

$$EAu_{,xx} + q_x = 0$$
$$-EI\theta_{,xx} - GA_s(w_{,x} - \theta) = 0$$
$$GA_s(w_{,xx} - \theta_{,x}) + q_y = 0$$



Alternative formulation

Discretized form from the derivation

$$\mathbf{K}^{\mathrm{e}} = egin{bmatrix} \mathbf{K}_{uu}^{\mathrm{e}} & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{K}_{ww}^{\mathrm{e}} & \mathbf{K}_{w heta}^{\mathrm{e}} \ \mathbf{0} & \mathbf{K}_{ heta w}^{\mathrm{e}} & \mathbf{K}_{ heta heta}^{\mathrm{e}} \end{bmatrix}, \quad \mathbf{a}^{\mathrm{e}} = egin{bmatrix} \mathbf{a}_{u}^{\mathrm{e}} \ \mathbf{a}_{w}^{\mathrm{e}} \ \mathbf{a}_{ heta}^{\mathrm{e}} \end{bmatrix}$$

with

$$\mathbf{K}_{uu}^{e} = \int_{\Omega} \mathbf{B}_{u}^{T} E A \mathbf{B}_{u} \, d\Omega$$

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$$\mathbf{K}_{w\theta}^{e} = -\int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{N}_{\theta} \, d\Omega$$

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$$\mathbf{K}_{\theta \theta}^{e} = \int_{\Omega} \mathbf{B}_{\theta}^{T} E I \mathbf{B}_{\theta} + \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{N}_{\theta} \, d\Omega$$

Alternative: collect all deformations in a single vector

$$oldsymbol{arepsilon} oldsymbol{arepsilon} egin{aligned} oldsymbol{arepsilon} & oldsymb$$

with

$$\mathbf{B} = egin{bmatrix} \mathbf{B}_u & \mathbf{0} & \mathbf{0} \ \mathbf{0} & \mathbf{B}_w & -\mathbf{N}_ heta \ \mathbf{0} & \mathbf{0} & \mathbf{B}_ heta \end{bmatrix}$$

The stiffness matrix takes a familiar form

$$\mathbf{K}^{\mathrm{e}} = \int_{\Omega} \mathbf{B}^T \mathbf{D} \mathbf{B} \, \mathrm{d}\Omega$$

with

$$\mathbf{D} = \begin{bmatrix} EA & 0 & 0\\ 0 & GA & 0\\ 0 & 0 & EI \end{bmatrix}$$



Objective: pure bending deformation ($\kappa \neq 0, \varepsilon = 0, \gamma = 0$):

Node 1:
$$u_1=w_1=0$$
, $\theta_1=-\frac{L^{\mathrm{e}}}{2}\kappa$, $N_1=1-\frac{x}{L^{\mathrm{e}}}$
Node 2: $u_2=w_2=0$, $\theta_2=\frac{L^{\mathrm{e}}}{2}\kappa$, $N_2=\frac{x}{L^{\mathrm{e}}}$
Interpolations: $u(x)=0$, $w(x)=0$, $\theta(x)=N_i\theta_i=\kappa x-\frac{L^{\mathrm{e}}}{2}\kappa$



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Solution: reduced integration

- Only evaluate shear strain at the centere (where $\gamma=0$ above)
- In Timoshenko beam: for terms that are not related to γ , 1 point is enough for exact integration
- Using only 1 point removes shear locking without side effects



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Alternative solution: mixed interpolation (quadratic for w, linear for θ)



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