CIEM5110-2: FEM, lecture 2.1

Derivation of the finite element method for Timoshenko beam elements

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Objectives

This lecture focuses on the formulation of the finite element method for Timoshenko beams

- Another example of how to go from PDEs to the FE formulation
- Specifically for a case with multiple fields and multiple equations
- Illustration of shear locking
- Stepping stone towards frame analysis for upcoming workshops

The basic ingredients

Some remarks:

- Notations follow from Track Base except:
	- θ instead of φ for rotations
	- y (and w) are pointing upward
- The strong form has two coupled ODEs
- There are two unknown fields: w and θ

The basic ingredients

Some remarks:

- Notations follow from Track Base except: $- \theta$ instead of φ for rotations
	-
	- $-y$ (and w) are pointing upward
- The strong form has two coupled ODEs
- There are two unknown fields: w and θ

The alternative would be an Euler beam:

- Single ODE but of 4^{th} order
- Not treated in this unit
- FE derivation is given in the book

Discretized form

The coupled structure remains visisble in the system of equations

$$
\begin{bmatrix} \mathbf{K}_{\theta\theta} & \mathbf{K}_{\theta w} \\ \mathbf{K}_{w\theta} & \mathbf{K}_{w w} \end{bmatrix} \begin{bmatrix} \mathbf{a}_{\theta} \\ \mathbf{a}_{w} \end{bmatrix} = \begin{bmatrix} \mathbf{f}_{\theta} \\ \mathbf{f}_{w} \end{bmatrix}
$$

with

$$
\mathbf{K}_{\theta\theta} = \int_{\Omega} \mathbf{B}_{\theta}^{T} E I \mathbf{B}_{\theta} + \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{N}_{\theta} d\Omega
$$

\n
$$
\mathbf{K}_{\theta w} = -\int_{\Omega} \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{B}_{w} d\Omega
$$

\n
$$
\mathbf{K}_{w\theta} = -\int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{N}_{\theta} d\Omega
$$

\n
$$
\mathbf{K}_{ww} = \int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{B}_{w} d\Omega
$$

\n
$$
\mathbf{f}_{\theta} = \int_{\Gamma_{M}} \mathbf{N}_{\theta}^{T} T d\Gamma
$$

\n
$$
\mathbf{f}_{w} = \int_{\Gamma_{V}} \mathbf{N}_{w}^{T} F d\Gamma + \int_{\Omega} \mathbf{N}_{w}^{T} q d\Omega
$$

$\widetilde{\mathbf{T}}$ U **Delft**

Extensible beam element

Combining the Timoshenko element with a bar element:

$$
\begin{bmatrix} \mathbf{K}_{uu}^{\text{e}} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_{ww}^{\text{e}} & \mathbf{K}_{w\theta}^{\text{e}} \\ \mathbf{0} & \mathbf{K}_{\theta w}^{\text{e}} & \mathbf{K}_{\theta\theta}^{\text{e}} \end{bmatrix} \begin{bmatrix} \mathbf{a}_{u} \\ \mathbf{a}_{w} \\ \mathbf{a}_{\theta} \end{bmatrix} = \begin{bmatrix} \mathbf{f}_{u} \\ \mathbf{f}_{w} \\ \mathbf{f}_{\theta} \end{bmatrix}
$$

with

$$
\mathbf{K}_{uu} = \int_{\Omega} \mathbf{B}_{u}^{T} E A \mathbf{B}_{u} d\Omega
$$

\n
$$
\mathbf{f}_{u} = \int_{\Gamma_{N}} \mathbf{N}_{u}^{T} F_{x} d\Gamma + \int_{\Omega} \mathbf{N}_{u}^{T} q_{x} d\Omega
$$

\n
$$
\mathbf{f}_{w} = \int_{\Gamma_{V}} \mathbf{N}_{w}^{T} F_{y} d\Gamma + \int_{\Omega} \mathbf{N}_{w}^{T} q_{y} d\Omega
$$

\n
$$
\mathbf{f}_{\theta} = \int_{\Gamma_{M}} \mathbf{N}_{\theta}^{T} T d\Gamma
$$

Now there are three coupled PDEs

$$
EAu_{,xx} + q_x = 0
$$

- $EI\theta_{,xx} - GA_s (w_{,x} - \theta) = 0$
 $GA_s (w_{,xx} - \theta_{,x}) + q_y = 0$

Alternative formulation

Discretized form from the derivation

$$
\mathbf{K}^{\text{e}} = \begin{bmatrix} \mathbf{K}_{uu}^{\text{e}} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{K}_{ww}^{\text{e}} & \mathbf{K}_{w\theta}^{\text{e}} \\ \mathbf{0} & \mathbf{K}_{\theta w}^{\text{e}} & \mathbf{K}_{\theta \theta}^{\text{e}} \end{bmatrix}, \quad \mathbf{a}^{\text{e}} = \begin{bmatrix} \mathbf{a}_{u}^{\text{e}} \\ \mathbf{a}_{w}^{\text{e}} \\ \mathbf{a}_{\theta}^{\text{e}} \end{bmatrix}
$$

with

$$
\mathbf{K}_{uu}^{\mathbf{e}} = \int_{\Omega} \mathbf{B}_{u}^{T} E A \mathbf{B}_{u} d\Omega
$$

\n
$$
\mathbf{K}_{ww}^{\mathbf{e}} = \int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{B}_{w} d\Omega
$$

\n
$$
\mathbf{K}_{w\theta}^{\mathbf{e}} = -\int_{\Omega} \mathbf{B}_{w}^{T} G A_{s} \mathbf{N}_{\theta} d\Omega
$$

\n
$$
\mathbf{K}_{\theta w}^{\mathbf{e}} = -\int_{\Omega} \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{B}_{w} d\Omega
$$

\n
$$
\mathbf{K}_{\theta \theta}^{\mathbf{e}} = \int_{\Omega} \mathbf{B}_{\theta}^{T} E I \mathbf{B}_{\theta} + \mathbf{N}_{\theta}^{T} G A_{s} \mathbf{N}_{\theta} d\Omega
$$

Alternative: collect all deformations in a single vector

$$
\boldsymbol{\varepsilon} \equiv \begin{Bmatrix} \varepsilon \\ \gamma \\ \kappa \end{Bmatrix} = \begin{Bmatrix} u_{,x} \\ w_{,x} - \theta \\ \theta_{,x} \end{Bmatrix} = \mathbf{Ba}^{\mathbf{e}}
$$

with

$$
\mathbf{B} = \begin{bmatrix} \mathbf{B}_u & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{B}_w & -\mathbf{N}_\theta \\ \mathbf{0} & \mathbf{0} & \mathbf{B}_\theta \end{bmatrix}
$$

The stiffness matrix takes a familiar form

$$
\mathbf{K}^{\text{e}} = \int_{\Omega} \mathbf{B}^T \mathbf{D} \mathbf{B} \, \mathrm{d}\Omega
$$

with

$$
\mathbf{D} = \begin{bmatrix} EA & 0 & 0 \\ 0 & GA & 0 \\ 0 & 0 & EI \end{bmatrix}
$$

Objective: pure bending deformation ($\kappa \neq 0, \varepsilon = 0, \gamma = 0$):

Node 1: $u_1=w_1=0, \qquad \theta_1= L^{\text{e}}$ 2 $\kappa, \qquad N_1 = 1 \mathcal{X}$ $\overline{L^{\text{e}}}$ Node 2: $u_2=w_2=0, \qquad \theta_2=0$ L^e 2 $\kappa, \qquad N_2 =$ \mathcal{X} $\overline{L^{\text{e}}}$ Interpolations: $u(x) = 0, \qquad w(x) = 0, \qquad \theta(x) = N_i \theta_i = \kappa x$ – L^e 2

κ

Objective: pure bending deformation ($\kappa \neq 0, \varepsilon = 0, \gamma = 0$):

Node 1:
$$
u_1 = w_1 = 0
$$
, $\theta_1 = -\frac{L^e}{2}\kappa$, $N_1 = 1 - \frac{x}{L^e}$

\nNode 2: $u_2 = w_2 = 0$, $\theta_2 = \frac{L^e}{2}\kappa$, $N_2 = \frac{x}{L^e}$

\nInterpolations: $u(x) = 0$, $w(x) = 0$, $\theta(x) = N_i \theta_i = \kappa x - \frac{L^e}{2}\kappa$

\nStrains: $\kappa = \theta_{,x} = \kappa \blacktriangledown$, $\varepsilon = u_{,x} = 0 \blacktriangledown$, $\gamma = w_{,x} - \theta = -\kappa x + \frac{L^e}{2}\kappa \blacktriangledown$

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Solution: reduced integration

- Only evaluate shear strain at the centere (where $\gamma = 0$ above)
- In Timoshenko beam: for terms that are not related to γ , 1 point is enough for exact integration
- Using only 1 point removes shear locking without side effects

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Alternative solution: mixed interpolation (quadratic for w , linear for θ)

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