

Advanced Time Series Econometrics

Week 3: High-dimensional Volatility Models

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Plan for Today

1. Introduction
2. The Zoo of Volatility Models
3. Estimating + Evaluating High-Dimensional Volatility Model

Introduction

Conditional Variance Matrix

Consider the random vectors (e.g., daily stock returns)

$$y_t = (y_{1,t}, \dots, y_{N,t})' \in \mathbb{R}^N, \quad t = 1, \dots, T$$

such that

$$\mathbb{E}[y_t \mid \mathcal{F}_{t-1}] = \mathbf{0}_N, \quad \text{Var}[y_t \mid \mathcal{F}_{t-1}] = H_t \in \mathbb{R}^{N \times N}$$

where

- the sigma-algebra \mathcal{F}_{t-1} contains information up to time $t - 1$
- H_t is the **conditional** (co)variance matrix measurable by \mathcal{F}_{t-1}
- Under stationarity: $\Sigma = \mathbb{E}H_t = \mathbb{E}[y_t y_t']$ is the unconditional variance matrix

Harvey (1989, JFE):

... The evidence indicates that the conditional covariances do change through time...

- Conditional variance matrix H_t of vector of asset returns y_t is relevant for:
 - Portfolio selection: mean-variance optimisation (diversification) requires reliable estimate of variance matrix over the holding period.
 - Hedging: trying to eliminate exposure to certain risk factors requires conditional betas, which are functions of H_t .
 - Risk management: Value at Risk of portfolio return $w'y_t$ depends on variance $w'H_t w$. If portfolio weights are time-varying, this requires H_t .
- Today we are interested in the high-dimensional regime with $N \asymp T$, although most -if not all- techniques still work for small N .
- High-dimensional GARCH models often suffer from curse of dimensionality; some proposals provide a partial solution.

Catch Up: Univariate GARCH

- Define the marginal variances

$$h_{i,t} = \text{Var}_{t-1}(y_{i,t}), \quad i = 1, \dots, N$$

where $\text{Var}_{t-1}(\cdot)$ is conditional on \mathcal{F}_{t-1} .

- Standard GARCH(1,1) specification for each series:

$$y_{i,t} = \mu_{i,t} + \varepsilon_{i,t} = 0 + h_{i,t}^{1/2} z_{i,t},$$

$$h_{i,t} = (1 - \alpha_i - \beta_i)\sigma_i^2 + \alpha_i \varepsilon_{i,t-1}^2 + \beta_i h_{i,t-1},$$

$$z_{i,t} \sim \text{IID}(0, 1).$$

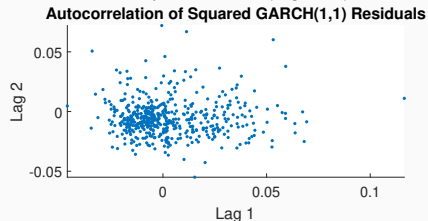
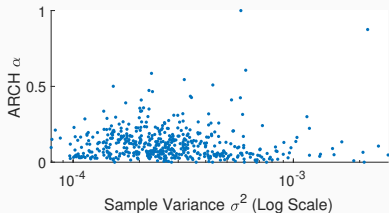
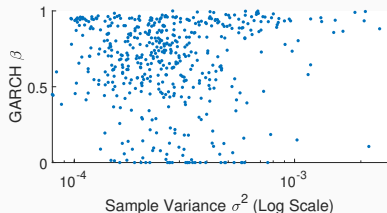
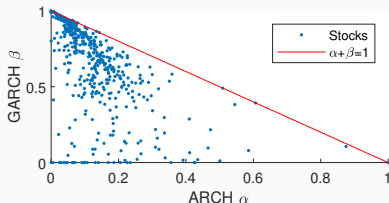
- Then decompose that

$$H_t = D_t Q_t D_t, \quad D_t = \text{diag}(h_{1,t}^{1/2}, \dots, h_{N,t}^{1/2}),$$

with

$$Q_t = \text{Var}_{t-1}(z_t), \quad z_t = (z_{1,t}, \dots, z_{N,t})'.$$

Example: 500 US Stocks from 2015–2019



$N = 500$ US Stocks with: (1) largest market value at the beginning of 2015 (2) a complete daily return history over 2015–2019 ($T = 1258$)

High-Dimensional Volatility Models

- Our focus today is to model and estimate Q_t
- The marginal GARCH parameters σ_i^2 , α_i , β_i can be fitted series-by-series.
- A trivial property we want to guarantee: H_t and Q_t are positive (semi)-definite
- For practitioners, one may want specification **flexible** enough to replicate properties such as
 - persistence in volatility and covariation;
 - time variation in correlation;
 - volatility spill-over effects;
 - asymmetries, leverage effects.
 - model is closed under linear transformations (taking portfolios)...

The Zoo of Volatility Models

DVEC Model: Bollerslev et al. (1988)

Analogous to univariate GARCH model, the (co)variances may depend on their own past, and on past squares $\varepsilon_{i,t-1}^2$ and cross-products $\varepsilon_{i,t-1}\varepsilon_{j,t-1}$:

$$H_t = (I - A - B) \circ \Sigma + A \circ (\varepsilon_{t-1}\varepsilon'_{t-1}) + B \circ H_{t-1}$$

where 'o' denotes the entrywise product (Hadamard product), and A, B are symmetric matrices.

- Involves parameters at the order $N^2 + 2N^2$.
- Marginal GARCH models: $A_{ii} = \alpha_i$, $B_{ii} = \beta_i$, $\Sigma_{ii} = \sigma_i^2$
- Q_t is the correlation matrix corresponding to H_t
- If taking A and B as scalars (implying that $\alpha_{ii} = \alpha$, $\beta_{ii} = \beta$):

$$H_t = (1 - \alpha - \beta)\Sigma + \alpha\varepsilon_{t-1}\varepsilon'_{t-1} + \beta H_{t-1}$$

parameters at the order $N^2 + 2$

- @UvA • RiskMetrics ($\alpha + \beta = 1$): $H_t = (1 - \beta)\varepsilon_{t-1}\varepsilon'_{t-1} + \beta H_{t-1}$

BEKK Model: Engle and Kroner (1995)

BEKK(1,1,K) Model:

$$H_t = C^{*'}C^* + \sum_{k=1}^K A_k^{*'}\varepsilon_{t-1}\varepsilon_{t-1}'A_k^* + \sum_{k=1}^K B_k^{*'}H_{t-1}B_k^*,$$
$$C^{*'}C^* = \Sigma - \sum_{k=1}^K A_k^{*'}\Sigma A_k^* - \sum_{k=1}^K B_k^{*'}\Sigma B_k^*$$

where A_k^* and B_k^* are non-singular $N \times N$ matrices, and C^* is $N \times N$ upper triangular matrix.

- Guarantee positive definiteness of H_t ;
- Setting $A_k^* = \text{diag}(a_k)$ and $B_k^* = \text{diag}(b_k)$ diagonal gives the DVEC model with

$$A = \sum_{k=1}^K a_k a_k', \quad B = \sum_{k=1}^K b_k b_k'.$$

Factor GARCH Model: Engle, Ng and Rothschild, 1990

$$y_t = \sum_{k=1}^K \lambda_k f_{kt} + e_t = \Lambda f_t + e_t,$$

where $\{f_{k,t} = w_k' y_t\}_{k=1}^K$ are independent GARCH processes, independent of $e_t \sim \text{IID}(0, \Omega^*)$.

- $\text{Var}_{t-1}(f_{k,t}) = h_{k,t} = (1 - \alpha_k - \beta_k)\sigma_k^2 + \alpha_k f_{k,t-1}^2 + \beta_k h_{k,t-1}$
- The conditional variance

$$H_t = \Sigma + \sum_{k=1}^K \lambda_k \lambda_k' (\alpha_k (f_{k,t-1}^2 - \sigma_k^2) + \beta_k (w_k' H_{t-1} w_k - \sigma_k^2))$$

- # parameters at the order $N^2 + KN$
- Special case of BEKK: Exercise 3

GO-GARCH Model

Consider the spectral decomposition of unconditional covariance matrix

$$\Sigma = PLP'$$

GO-GARCH (Alexander, 2002; van der Weide, 2002; Vrontis, Dellaportas and Pollitis, 2003):

$$y_t = \Lambda f_t, \quad H_t = \Lambda V_t \Lambda'$$

where $\Lambda = PL^{1/2}U'$ is a non-singular matrix, U is some orthogonal matrix, and f_t is an N -dimensional vector of independent GARCH processes, with diagonal variance matrix V_t , and with unit unconditional variance.

- Closed under non-singular transformations;
- # parameters at the order $N^2 + N^2 + N$
- If $U = I$ then $N^2 + N$

The **constant** conditional correlation (CCC) model

$$H_t = D_t Q D_t, \quad D_t = \text{diag}(h_{11,t}^{1/2}, \dots, h_{NN,t}^{1/2}),$$

where $Q = \mathbb{E}[z_t z_t']$ is the covariance/correlation matrix of 'devolatilized' residuals z_t .

- Positive definite;
- # parameters of order $N^2 + N$;
- Not closed under linear transformations.

DCC Model: Engle (2002)

The **dynamic** conditional correlation (DCC) model :

$$H_t = D_t \mathbf{R}_t D_t, \quad D_t = \text{diag}(h_{11,t}^{1/2}, \dots, h_{NN,t}^{1/2}),$$

where R_t is a conditional correlation matrix, given by

$$R_t = \text{diag}(Q_t)^{-1/2} Q_t \text{diag}(Q_t)^{-1/2}$$

$$Q_t = (1 - \alpha - \beta) \Sigma + \alpha z_{t-1} z'_{t-1} + \beta Q_{t-1}$$

Here $\Sigma = \mathbb{E}Q_t$

- Positive definite;
- More flexible than CCC with 2 more parameters (α, β) ; not closed under linear transformations;
- Correction proposed by Aielli (2013, JBES): makes little difference in practice.

GAS Model: Creal, Koopmans and Lucas (2011)

The **generalized autoregressive score (GAS)** model builds on the DCC model, with

$$f_t = \begin{pmatrix} \text{diag}(D_t^2) \\ \text{vech}(Q_t) \end{pmatrix}$$

satisfying

$$f_t = \omega + A s_{t-1} + B f_{t-1}, \quad s_t = S_t \times \nabla_{f_t} \log p(y_t | f_t; \theta)$$

By taking p to be the multivariate $t(\nu)$ density, this gives an automatic model specification that downweights extreme observations. In particular,

$$Q_t = (1 - \beta) \Sigma + \alpha \tilde{S}_{t-1} \nabla_{Q_{t-1}} \log p(y_{t-1} | f_{t-1}; \theta) + \beta Q_{t-1}$$

- Equity returns display leverage effects: large negative shocks have stronger effect on volatility than large positive shocks.
- One can use asymmetric *univariate* GARCH models

$$h_{i,t} = \omega_i + (\alpha_i + \gamma_i \mathbb{1}[\varepsilon_{i,t-1} < 0]) \varepsilon_{i,t-1}^2 + \beta_i h_t$$

on the factors $\varepsilon_{i,t} = f_{i,t}$ or returns $\varepsilon_{i,t} = y_{i,t}$

- Can be included in a DCC model by

$$Q_t = (1 - \alpha - \beta) \Sigma + \alpha z_{t-1} z'_{t-1} + \beta Q_{t-1} + \gamma (v_{t-1} v'_{t-1} - \Sigma_-),$$

where $v_t = \max(0, -z_t) = -\mathbb{1}[z_t < 0] \circ z_t$ and $\Sigma_- = \mathbb{E}[v_t v'_t]$.

Estimating + Evaluating High-Dimensional Volatility Model

Estimation of multivariate GARCH models

- The log-(quasi-)likelihood for the model

$$y_t | \mathcal{F}_{t-1} \overset{\text{quasi}}{\sim} N(0, H_t(\theta))$$

is given by $\ell(\theta) = \sum_{t=1}^T \ell_t(\theta)$, with

$$\ell_t(\theta) = -\frac{N}{2} \log 2\pi - \frac{1}{2} \log |H_t(\theta)| - \frac{1}{2} y_t' H_t(\theta)^{-1} y_t.$$

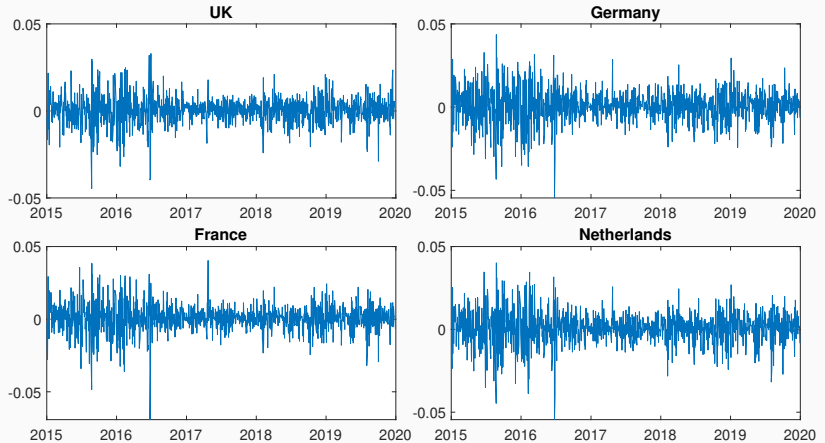
- For GAS model one may use the likelihood $t(\nu)$ and include ν as a parameter too
- Depending on N and the specification of $H_t(\theta)$, the dimension of the parameter space can be very high
- For (very) small $N/T < 100$, ML works fine. For specific models, multi-step approximations to ML have been proposed.
- For large $N \asymp T$, ML suffers from overfitting

Estimating Low-Dimensional GARCH Models

For small $N/T < 100$, say:

- For **GO-GARCH**, this is adapted as follows, using $y_t = \Lambda f_t$, $\Lambda = PL^{1/2}U$:
 1. Estimate P and L as eigenvectors and eigenvalues of sample variance matrix of y_t . Hence $\hat{s}_t = \hat{L}^{-1/2}\hat{P}'y_t$;
 2. Maximize the log-likelihood for the model $f_t = U'\hat{s}_t$, over orthogonal matrices U (if unknown) and univariate GARCH parameters for f_{it} ;
 3. U may also be estimated from the (cross-) autocorrelations in $\hat{s}_t\hat{s}_t'$: Boswijk and van der Weide (2011)
- For **DCC**, a three-step estimation procedure is:
 1. Estimate GARCH models for y_{it} , and compute $\hat{z}_{it} := \hat{h}_{i,t}^{-1/2}y_t$;
 2. Estimate $\Sigma = \mathbb{E}Q_t$ by $S = T^{-1}\sum_{t=1}^T \hat{z}_t\hat{z}_t'$.
 3. Maximize $-\frac{1}{2}\sum_{t=1}^T (\log |R_t| + \hat{z}_t'R_t^{-1}\hat{z}_t)$ over correlation dynamic parameters.

Example: European Stock Market Indices, 2015–2019



Daily Return On European Stock Market Indices

Example: Estimated DCC Model

- Univariate GARCH(1,1) models:

	UK	Germany	France	Netherlands
$\hat{\sigma}_i$	0.0078	0.0097	0.0098	0.0096
$\hat{\alpha}_i$	0.0237	0.0186	0.0050	0.0093
$\hat{\gamma}_i$	0.2041	0.1935	0.1284	0.2332
$\hat{\beta}_i$	0.8061	0.8376	0.9057	0.8509

- Sample correlation matrix of \hat{z}_t

$$S = \begin{bmatrix} 1.0000 & 0.7366 & 0.7423 & 0.7859 \\ 0.7366 & 1.0000 & 0.8690 & 0.8860 \\ 0.7423 & 0.8690 & 1.0000 & 0.9063 \\ 0.7859 & 0.8860 & 0.9063 & 1.0000 \end{bmatrix}$$

- Correlation dynamics: $\hat{\alpha} = 0.0683$, $\hat{\beta} = 0.8764$.

Estimating Large-Dimensional Covariance Matrix

- Most - if not all - models involve estimating the **unconditional** covariance matrix in some sense:

$$\Sigma = \mathbb{E}H_t \quad \text{or} \quad \Sigma = \mathbb{E}Q_t$$

- In general, the sample covariance matrix

$$S = \frac{1}{T} \sum_{t=1}^T y_t y_t' = \frac{1}{T} Y' Y, \quad Y = [y_1, \dots, y_T]' \quad \text{or}$$

$$S = \frac{1}{T} \sum_{t=1}^T \hat{z}_t \hat{z}_t' = \frac{1}{n} \hat{Z}' \hat{Z}, \quad Z = [\hat{z}_1, \dots, \hat{z}_T]'$$

is **inconsistent** towards Σ in high dimensions with $N \asymp T$; even if one replace \hat{z}_t with z_t .

- In particular, $\|S - \Sigma\|_F^2 = \|\text{vec}(S) - \text{vec}(\Sigma)\|^2 \xrightarrow{\mathbb{P}} 0$.

Rotation Equivariant Estimator

- Consider the spectral decomposition of sample covariance matrix S given by

$$S = U\Lambda U', \quad U = [u_1, \dots, u_N], \quad \Lambda = \text{diag}(\lambda_1, \dots, \lambda_N).$$

- The sample covariance matrix $S = S(Y') = \frac{1}{T} Y'Y$ is rotation equivariant: for all orthogonal matrix W

$$S(WY') = WS(Y)W'$$

- The class of rotation equivariant estimator is of the form

$$\hat{\Sigma} = U\hat{\Lambda}U', \quad \hat{\Lambda} = \text{diag}(d_1, \dots, d_N),$$

where d_i are invariant with respect to data rotations.

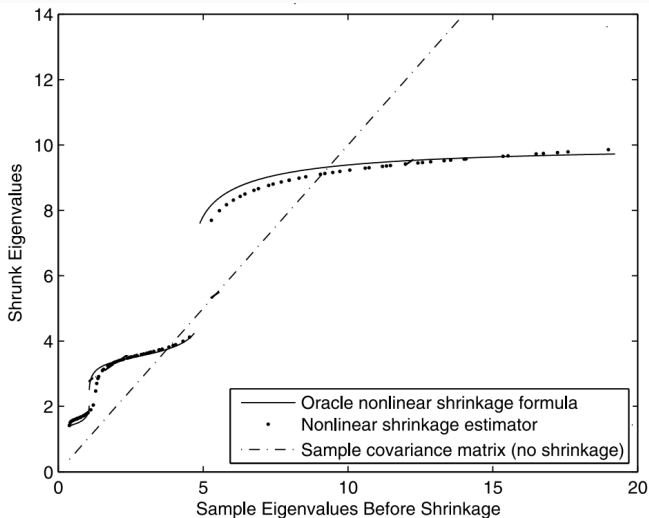
Optimal Rotation Equivariant Estimator

The sum of squared errors over all entries

$$\begin{aligned}\left\|\hat{\Sigma} - \Sigma\right\|_F^2 &= \left\|\hat{\Lambda} - U'\Sigma U\right\|_F^2 \\ &= \sum_{i=1}^N (d_i - u_i'\Sigma u_i)^2 + \underbrace{\sum_{i \neq j} (u_i'\Sigma u_j)^2}_{\xrightarrow{\mathbb{P}} 0}\end{aligned}$$

is minimized with $d_i = u_i'\Sigma u_i =: d_i^*$.

- Ledoit and Péché (2011): $d_i^* \approx \delta(\lambda_i)$ for some shrinkage function δ for $Y' = \Sigma^{1/2}Z'$ for Z with i.i.d. entries
- Ledoit and Wolf (2012): (Consistent) Estimation of δ

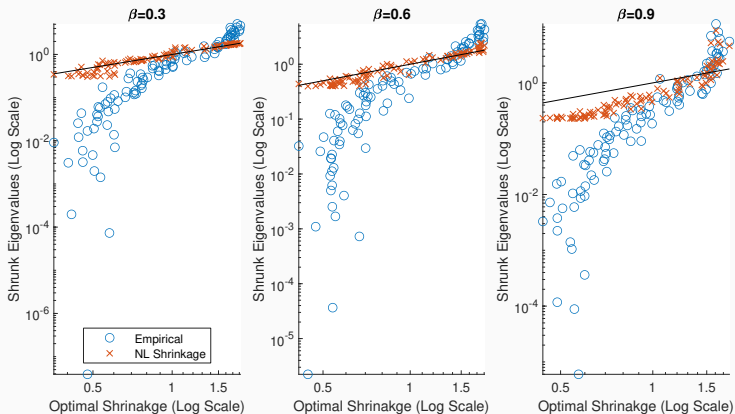


A typical simulation result for IID data with $N = 100$ and $T = 300$ in Ledoit and Wolf (2012): 20% of population eigenvalues of Σ are equal to 1, 40% are equal to 3 and 40% are equal to 10.

- For each asset, fit a univariate GARCH(1,1) model and use the fitted model to devolatilize the return series.
- Take LW2012's nonlinear shrinkage estimator 'off the shelf' and apply them to devolatilized returns \hat{z}_t to get $\hat{\Sigma}$ (inconsistent but 'optimal' in terms of squared errors)
- Plug in $\hat{\Sigma}$ and then fit the remaining 2 DCC model parameters $\hat{\alpha}, \hat{\beta}$ using the composite likelihood method in Pakel et al.(2021).

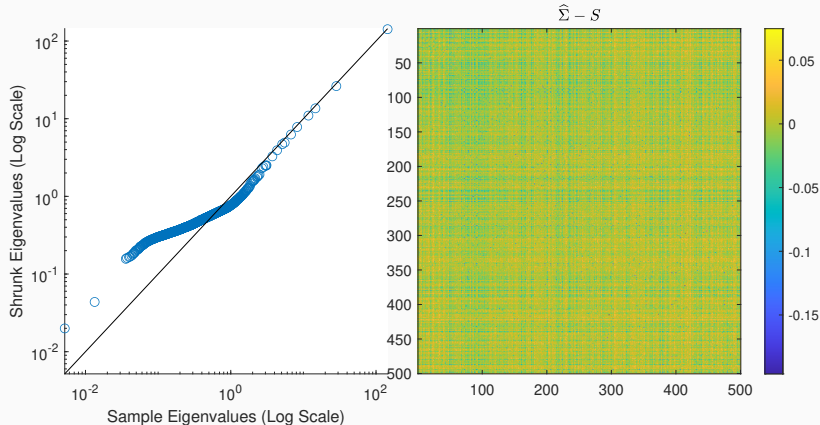
Simulation: Estimating Σ in DCC model

- Univariate GARCH: $\sigma_i^2 = 1$, $\alpha_i = 0.05$, $\beta_i = 0.9$
- Correlation dynamics: $\alpha = 0.05$, $\beta \in \{0.3, 0.6, 0.9\}$



Improvement $1 - \frac{\|\hat{\Sigma} - \Sigma\|_F^2}{\|S - \Sigma\|_F^2} = 87.0\%, 87.3\%, 47.6\%$ from left to the right

Example: 500 US Stocks from 2015–2019



Correlation dynamics

- with shrinkage: $\hat{\alpha} = 0.0417$ and $\hat{\beta} = 0.8136$

<https://youtu.be/SeDwJfykgqA>

- without shrinkage: $\hat{\alpha} = 0.0413$ and $\hat{\beta} = 0.8083$

Evaluating High-Dimensional Volatility Model

- Diagnostic testing are possible (only) in low dimensions: see Bauwens et al.(2006)
- In high dimensions, performance in risk management may be evaluated by testing implied Value at Risk for portfolio $w'y_t$. (Joint test of specification of H_t and distributional assumption.)
- ... or testing standardized residuals $SR_t = \frac{(w'_t y_t)^2}{w'_t H_t w_t}$ via the regression

$$SR_t = \mu + \rho SR_{t-1} + \nu_t$$

- ... or checking the excess variance of the implied minimum-variance portfolio
- ... or tracking error of a particular portfolio

1. Show that the matrix H_t defined by the BEKK model is positive definite.
2. Show that the BEKK model is a special case of the general VEC model specified by Equation (4) in Bollerslev et al.(1988), using the property $\text{vec}(ABC) = (C' \otimes A)\text{vec}(B)$ for conformable matrices A , B and C , and the duplication matrix D_N , defined by $\text{vec}(A) = D_N\text{vech}(A)$ for a symmetric $N \times N$ matrix A .
3. Show that the factor model is a special case of the BEKK model.